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(54) Microprocessor emulation

(57) Data processing means adapted to be controlled by sequential instructions, a substantial number of which comprise an operation code selected from a set of n such codes and a qualifying code selected from a set of m such codes, comprises a store having approximately n times m locations with each location corresponding to a consistent combination of operating code and qualifying code and holding a series of instructions corresponding to the said operating code and qualifying code. The qualifying code may be the addressing mode and a jump table 18 of 256 x 256 entries may be employed to access the instruction series. The use of both codes to access the jump table enables code strings of a host processor (e.g. 68020) to be accessed quickly by the op-code and immediately succeeding byte in an instruction of a processor (e.g. 8088) being emulated and avoids the need for routines to analyse the addressing mode.

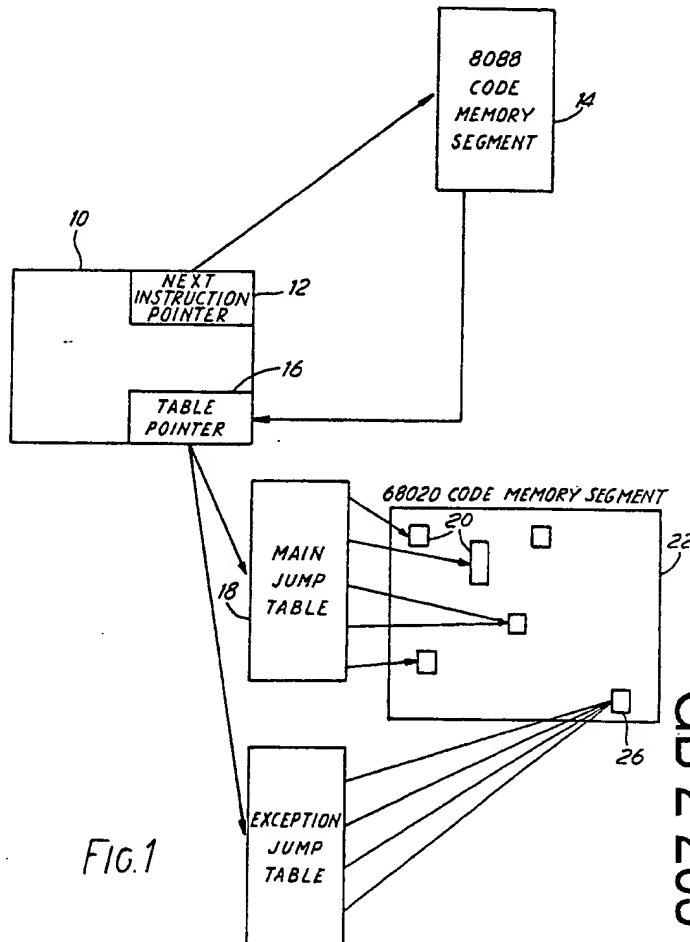


FIG. 1

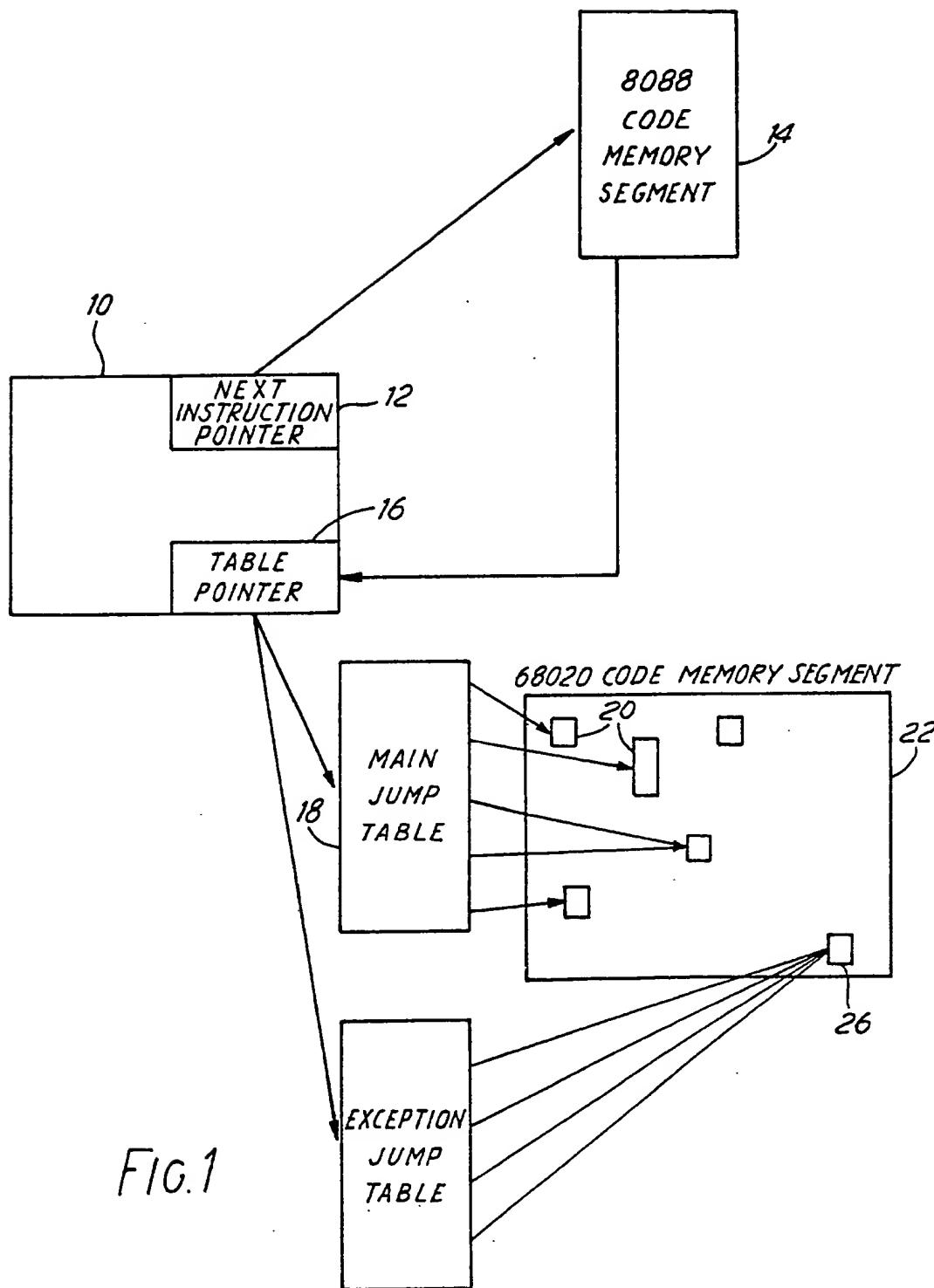
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The drawing(s) originally filed was (were) informal and the print here reproduced is taken from a later filed formal copy.

The specification as filed includes a computer program which is not here reproduced; it may be inspected in accordance with Section 118 of the Patents Act 1977.

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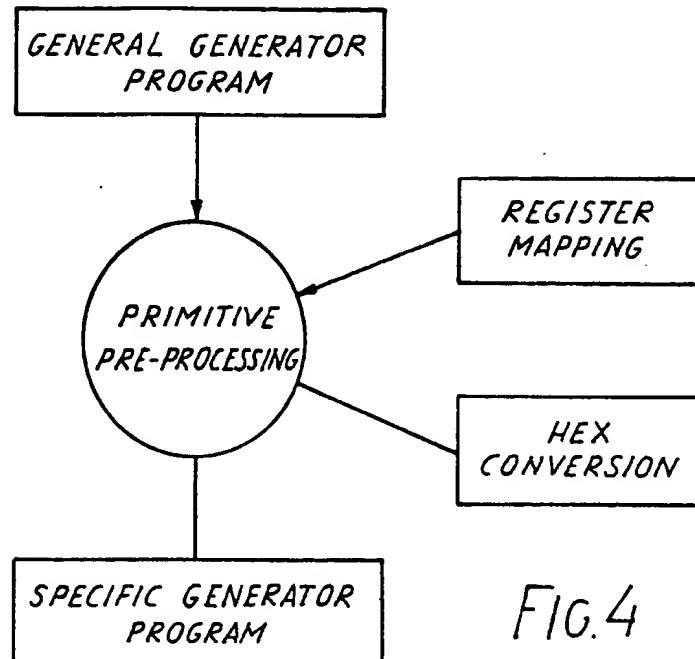


FIG.4

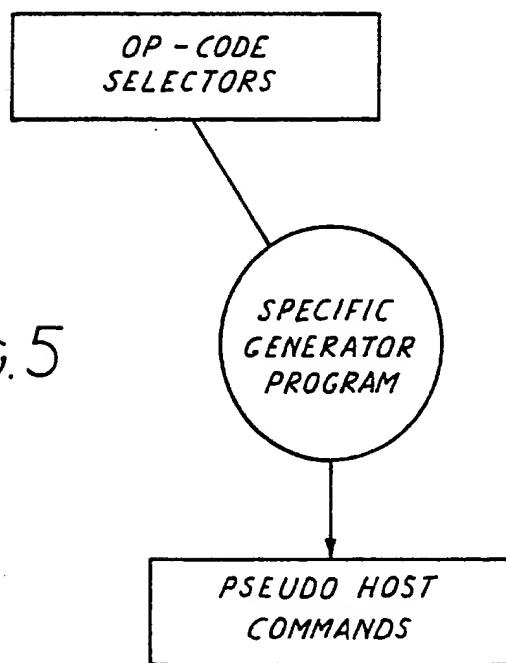


FIG.5

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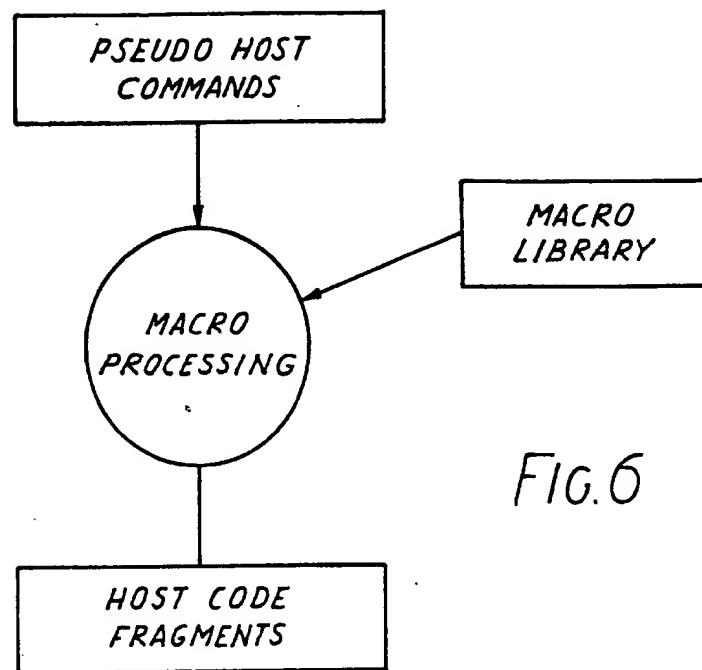


FIG.6

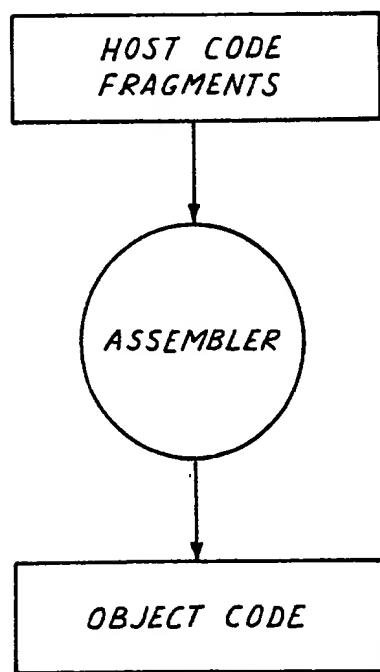


FIG.7

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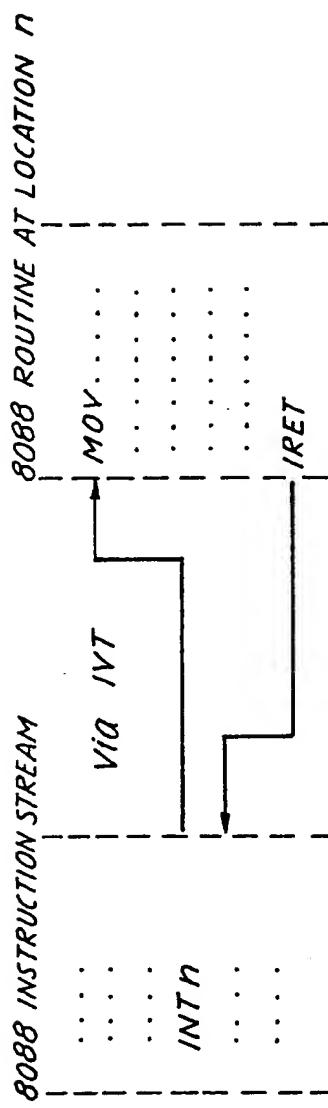


FIG. 11(a)

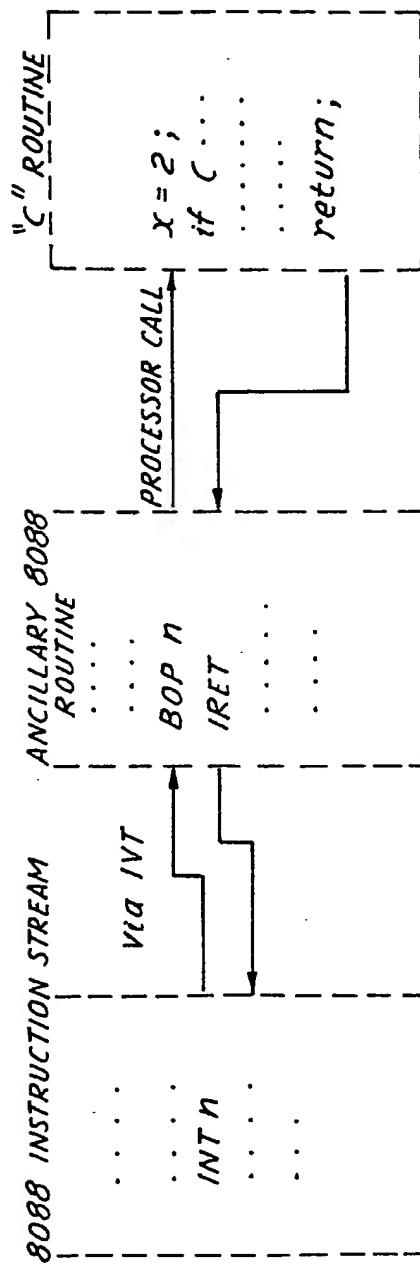


FIG. 11(b)

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IMPROVEMENTS IN DATA PROCESSING MEANS

This invention relates to data processing.

There exists a variety of commercially available processors which are capable of providing the central processing unit of a computer. Each processor can perform arithmetic, logical and control instructions and is adapted to cooperate with a particular organisation of memory and input and output devices. To a large extent, the instructions and the manner of addressing data held in the processor or stored in memory, are characteristics of a particular processor or family of processors. As a result, computer programs written for one computer - or range of computers based on a like processor - are frequently unsuitable for use with computers based on a different processor.

It is the case that a large body of commercially available software is based on a common operating system which can run only on particular processors. Computers which are based upon an incompatible processor are not capable of using such software even though the processor may in certain technical respects be superior to the processor for which the software is written. This problem of incompatibility has been recognised and attempts have been made to deal with the problem in two different ways. First, it has been suggested to provide in a computer based on a selected first processor, a second processor serving as a co-processor to provide the necessary compatibility. This obviously involves cost penalties. Second, it has been proposed to provide software by which the existing first processor is caused to emulate a different second processor. To

be of practical utility, the emulation must not involve a significant drop in effective processing speed and this presents enormous difficulties, even where the processor being used is inherently faster than that being emulated so that the additional processing required by the emulation is to some extent offset by faster processing. It will be recognized that speed is important not only because a user may demand a fast response time, but also because a particular effective processing speed or minimum processing speed is essential for the correct functioning of certain programs.

This invention focuses on the software emulation approach and for clarity hereafter the term "host" will be used to mean the processor which is through software caused to emulate a different processor (the emulated processor).

In what follows, particular attention will be paid to microprocessors though it should be understood that either or both of the host and emulated processors might take other forms.

To take a specific example, consider emulation of the microprocessor manufactured by Intel Corporation and referred to as 8088. This has an instruction set whose instructions are defined by some number of 8-bit bytes the first of which is an operating code (op-code). The instruction set comprises approximately 230 op-codes (not all possible instruction labels being used). Most instructions require one or more operands and the second byte of those instructions may be regarded as defining the mode of addressing the operand. This may recite specific memories or registers and may occasionally include

data. In other microprocessors, it may be a byte other than the second byte of the instruction which performs a function comparable to that of the 8088 addressing mode

If it is desired to emulate the operation of the 8088 microprocessor, several characteristics of that processor must be emulated. Chiefly, the instruction set of the 8088 must be mapped on to that of the host microprocessor. Inevitably, there will not be a one to one mapping. In addition it will be necessary to recreate, using the facilities of the host microprocessor, the many permutations of addressing modes provided by the 8088. To interpret instructions using prior art techniques would require for each operating code (that is to say the first byte of each instruction) a routine which was capable of analysing the second and subsequent bytes of the instruction and providing an appropriate series of instructions in the instruction set of the host microprocessor. Having regard to the facts that there would inevitably be no direct mapping of operations between the emulated microprocessor and the host microprocessor and that there are likely to be differences in registers and memory addressing, the subroutine corresponding to each 8088 operating code would be complex and would typically involve a number of conditional statements serving to distinguish between different addressing modes. Running such a complex subroutine for every instruction, inevitably slows down processing. Further complications will arise in dealing with the flags (such as auxiliary carry and parity) which are provided by the 8088 but not by the host, and in handling interrupts.

It is one object of this invention to provide for the emulation of a microprocessor without a significant loss of effective speed. It is recognised that emulation will inevitably involve additional processing but its significance must be judged in terms of the processing speed of the host microprocessor. It is anticipated that the host microprocessor will have a faster processing speed than the microprocessor it is desired to emulate (perhaps by an order of magnitude) and the additional processing associated with the emulation will not result in a significant loss of effective speed provided that the amount of additional processing is of the same order or less than the increase in processing speed of the host.

Accordingly, the present invention consists, in one aspect, in data processing means adapted to be controlled by sequential instructions, a substantial number of which comprise an operation code selected from a set of n such codes and a qualifying code selected from a set of m such codes, the data processing means comprising a store having approximately n times m locations with each location corresponding to a consistent combination of operating code and qualifying code and holding a series of instructions corresponding to the said operating code and qualifying code.

By "qualifying code" is meant the next most significant byte or other discrete element in the instruction, after the instruction code.

In another aspect, the present invention consists in a process for controlling the operation of a data processing unit in accordance with a received series of instructions, where at least some

instructions each comprise an operator and an operand addressor, there being a finite number of permissible combinations of operator and operand addressor, the process comprising the steps of holding a plurality of instruction strings, one for each said permissible combination of operator and operand addressor, and inputting to the data processing unit for each received instruction, the instruction string corresponding with said operator and operand addressor combination.

In a still further aspect, the present invention consists in a computer including processing means; first store means for storing a series of instructions, a substantial number of which instructions comprise an operator and an addressing mode; second store means having a plurality of locations corresponding respectively with permissible combinations of said operator and said addressing mode, and being adapted to hold at each said location an instruction string; and control means adapted to input in sequence to said processing means instruction strings from locations in said second store means corresponding respectively with instructions from said first store means.

Preferably, the computer further comprises table means having entries corresponding with respective said locations, each entry comprising the address in said second store means of the said instruction string.

Advantageously, each instruction string is arranged to provide said control means with information relating to the address in said store means of the next instruction.

This invention will be described by way of example, with reference to the accompanying drawings in which:-

Figure 1 is a diagrammatic representation of aspects of the invention,

Figures 2A, 2B and 2C are listings of certain code strings in the language of the host microprocessor;

Figure 3 is a listing illustrating means for generating the code strings exemplified by the extracts of Figures 2A, 2B and 2C;

Figures 4, 5, 6 and 7 are flow charts illustrating the operation of said generator means;

Figure 8 is an extract from the listing of the general generator Program as shown in Figure 4;

Figure 9 is an extract from the listing of the pseudo commands shown in Figure 5,

Figure 10 is an excerpt from the listing of the macro library shown in Figure 6 and

Figures 11A and 11B illustrate in diagrammatic form an interrupt technique according to the prior art and to the present invention respectively.

This description will continue to take as an example of a microprocessor whose operation is to be emulated, the 8088 chip manufactured by Intel Corporation, and will take as an example of a host microprocessor the MC68020 chip manufactured by Motorola Corporation. Before proceeding to a detailed description of the invention, it would be helpful to outline certain relevant aspects of the 8088 chip.

Two extremely important characteristics of the 8088, as with any other microprocessor, are the instruction set and the manner in which the addressing of data is handled. The instruction set includes arithmetic, logical and control instructions and takes the machine code form of a single byte op-code. There are, for example, six op-codes corresponding to the arithmetic assembly instruction ADD; the op-codes distinguishing between byte and word operation and between, for example, memory and register operands. The operand itself is defined in the second and - if necessary - succeeding bytes of the instruction string, it being recognised that certain op-codes demand no operand.

Data which is to be operated upon can be addressed in a variety of addressing modes. The data itself could for example form part of the instruction or be located in a processor register named in the instruction. Alternatively, the instruction could contain the address in memory at which the data is located or might state the register containing the address or the registers which require to be summed to

obtain the memory address. The skilled man will be aware of still further addressing modes.

As outlined above, attempts have hitherto been made to emulate the 8088 using each op-code in the instruction string as the address in a single byte look up table which, for each op-code, point to necessary coding (in the machine language of the host microprocessor) to enable analysing of the addressing mode and other information contained in succeeding bytes of the instruction stream and to execute the decoded instruction. The difficulty with this approach is that the very flexibility in addressing modes which contributes to the power of the 8088 microprocessor results in coding strings of significant length and complexity for many of the op-code possibilities. As will be recognised, this means that the emulation runs at a slower effective speed than the microprocessor that is being emulated, unless the host microprocessor has a considerably faster processing speed.

According to this invention, a look up or jump table is provided which is addressed by each op-code and the immediately succeeding byte in the instruction stream. With nominally 256 possibilities for both the op-code and the next succeeding byte, the table accordingly has (nominally) 64K entries. From the very nature of the jump table - in which every consistent combination of op-code and addressing mode is represented a jump to any one location "implies" the addressing mode which is employed, without the need for decoding as such. Each entry in the jump table contains the address in memory of an instruction string in MC68020 code which will perform the equivalent function to

the 8088 instruction. The 68020 coding which is required is straightforward (as compared with prior software emulations) since no decoding of the addressing mode is required. The need for conditional statements in the emulation coding is substantially avoided.

By way of further explanation, reference is directed to Figure 1 which is in diagrammatic form. The microprocessor 10 provides a "next instruction pointer" 12 whose function is to point to the next 8088 instruction held in code memory segment 14. In the 8088, the base or datum point of the instruction list is held in a code segment register. The address relative to the base address of the next instruction in the instruction stream (which may be regarded as the logical address) is held in a separate register referred to as the instruction pointer. This is in the most usual case incremented by an amount corresponding to the length of the last instruction although jumps can also be provided for. The physical memory address, which is 20 bits in the 8088, is constructed by adding the 16 bit content of the instruction pointer (logical address) to the 16 bit content of the code segment register (base address) with four low order zero's appended. In the present arrangement, the 68020 register a5 is used to hold the sum of the base address, the logical address and the base of the pseudo 8088 code memory segment. This makes the content of a5 a "physical" 32 bit 68020 memory address. This avoids the need for repeated add functions. If necessary (because of a jump or segment relocation, for example) the logical address can be reconstituted from a5 by subtraction.

In accordance with this invention, the fetched instruction is not executed directly by the processor, but the first two bytes are used in table pointer 16 to point to the appropriate entry in the 64K jump table 18. For a reason which will be described hereafter, the table pointer 16 includes a base table pointer (in 68020 register a4) acting as a base to the jump table addresses. Each jump table entry provides the 32 bit start address of an instruction string 20 in 68020 code memory segment 22. These instructions are then executed.

Reference is now directed to Figure 2A which is a listing of a number of 68020 instruction strings relating to the POP op-code which is taken as an example of an 8088 op-code. As will be understood, the POP command transfers the word at the current top of the stack to the destination operand. According to the addressing mode, the destination operand may be a register or may be a memory location pointed to by a particular register or combination of registers, with or without a displacement defined in the third or subsequent instruction bytes. The instruction strings are referred to by the label OXXAYY where XX is in hexadecimal the op-code and YY the addressing mode. In a typical situation, the addressing mode takes the form MOD 000 R/M where MOD represents the first two bits and states whether the three bit R/M element is to be regarded as defining the destination operand as a register or as a pointer in register to the destination operand in memory, with or without a displacement. Taking examples in turn from Figure 2A, label 08FA00 represents, in decoded form, op-code 10001111 (binary) and addressing mode code 00 000 000 where the addressing mode code has been broken up to identify

the MOD and R/M components. In the first example, the destination operand is pointed to by the sum of registers BX (general register) and SI (source index), this being the meaning assigned to the R/M value 000 with an MOD value of 00. The 68020 coding at this location performs the POP function using essentially ADD and MOVE instructions. A detailed analysis of the coding is not believed to be necessary for an understanding of the invention but it can be identified that the destination address is first decoded from registers BX and SI, a word moved from the stack to that address and the stack pointer incremented by two so as to point to the next word in the stack.

Comparing the coding at the next location which corresponds to addressing mode 01 000 000, it would be seen that the coding is very similar but includes in the address computation a displacement. This is a single byte displacement as signified by an MOD value of 01. The next following location has a two byte displacement as signified by the MOD value 10.

With an op-code requiring both source and destination operand, the addressing mode may take the form MOD REG R/M where REG identifies the word, byte and segment registers. For such an op-code, there are of course a greater number of permissible addressing modes and accordingly a greater number of entries in the jump table and corresponding 68020 code strings. Still other op-codes may take an addressing mode of further modified form.

If two contiguous op-codes are both of a kind requiring no operand, the address in the jump table can be of a string of 68020

code performing both instructions. This gives a net increase in speed.

By the way of further explanation, reference is drawn to Figure 2A and particularly to the entries under labels 05bA00 and 05bA58. The 8088 op-codes 58 to 5f (hexadecimal) are instructions which require no separate operands; the operand being implied within the op-code. Thus op-code 5b pops a word to register BX. Turning to Figure 2A it will be seen that the code string under label 05ba00 performs that function. If the second byte of the 8088 instruction is a further command of the same type (e.g. 58) the processor will by executing the code string shown under label 05bA58 execute both POP instructions, that is to say POP to BX followed by POP to AX. This optimisation procedure covers, in the present example, those register and segment variants of the POP and PUSH commands.

If the second byte of the instruction stream is not a POP or PUSH command, the jump table points in each case to the code string shown (in this example) under label 05bA00, the op-code pointer in a5 is incremented by one only and the second byte is treated as the first byte of the next instruction.

It will be recognised that in an emulation, means has to be provided for updating the information pointer analogue. According to a preferred feature of the present invention the coding which performs this task is contained at the end of substantially each 68020 code string. That is to say each code string provides for incrementing of the register a5 (analogous to the 8088 information pointer) by an amount equal to the length of the corresponding 8088 instruction.

Referring again to the code strings shown in Figure 2, it will be noted that an add instruction of the form addql#x,a5 is included at every location. This is consistent throughout the entire array of 68020 code strings.

This increments the op-code pointer in register a5 by the number x of bytes occupied by the current instruction. Thus it will be seen that the coding for location 08FA00 includes the instruction of addql #2,a5, the 8088 instruction being a 2 byte instruction. As explained above that the following code string refers to the same op-code with an addressing mode that includes a displacement which (in MOD 01) is an 8-bit displacement extended to 16 bits. The operand accordingly requires 2 bytes, the entire instruction occupies 3 bytes and the coding is provided for incrementing by 3 the op-code pointer in register a5. In the next string, a 16-bit displacement is employed, the instruction requires 4 bytes and coding is provided to add 4 to the op-code pointer.

In addition to incrementing the op-code pointer, the code string serves through move and jump commands (in particular:-

move a5@,d4; jra a4@(d4:1:4) to take the processor directly to the 68020 code string whose address is contained in the jump table entry pointed to by the next 8088 instruction. It will be noted that the jump is made with respect to a base table pointer held in register a4, as noted above.

The penalty in memory space paid for adding this extra coding to every string is negligible, but the ability to move directly to the

68020 instruction string corresponding to the next 8088 instruction does provide a significant advantage in processing time.

It will be well known to the skilled man that under certain situations it is necessary to depart from the strict sequence of "fetch, execute, fetch, ..." instructions described above. This will usually involve the use of so-called interrupts. These may be used to enable the microprocessor to interact with input or output devices operating at different speeds. The interrupt mechanism can also be used to divert control from the microprocessor to a special routine held in memory.

It has been mentioned above that a particular difficulty in emulation arises with providing an interrupt handling capability. In the normal case, asynchronous interrupt requests that are supplied to the 8088 will only take effect at the end of the current instruction. With the emulation, however, it cannot be guaranteed that an interrupt will not occur part way through a 68020 code string, possibly causing a crash. In accordance with a preferred feature of this invention, an asynchronous interrupt is caused to alter the jump table base point in $a4$. This has no immediate effect but at the end of the current 68020 instruction string, the instruction $jra\ a4@(d4:1:4)$ causes a jump to be made not to the main jump table as previously described but to an exception jump table. This is illustrated in Figure 1 at 24. This exception jump table again has 64K entries but each points to a common piece of coding 26 in the 68020 code memory segment which processes the interrupt. A similar technique is used to deal with segment override.

It has been mentioned that the 8088 maintains a series of flags, these comprising three control flags and six status flags. Many of the arithmetical op-codes affect the status flags in particular and it is an essential requirement of a workable emulation of the 8088 processor that the information embodied in the flags be available for immediate access. In one approach, the coding at each location of the jump table corresponding with an op-code known to affect flags would update analogous flags held in one or more registers of the host microprocessor. In accordance with a preferred feature of this invention, however, an alternative approach is adopted and no attempt is made to keep all flags continuously updated. Rather, the necessary information is held to enable generation of the flags immediately a request is received for access to the flags. Taking into account the expected frequency of operations which, on the one hand affect flags and on the other are dependent upon flag information, the approach preferred in this invention represents a significant saving in processing time.

By way of further explanation, the 8088 processor uses bit 2 of the status word as a parity flag. This is arranged to hold at all times the parity of the last byte result and is used, for example, in instructions such as "Jump on the parity". It happens that the 68020 processor does not automatically maintain a parity flag. According to the preferred feature of the present invention, any 68020 code string which performs the function of an 8088 instruction affecting parity, is arranged to leave the last result byte in register d2. Reference is drawn, for example, to Figure 2B which is the 68020 code string for

the label 001A00, being one of the ADD instructions. It will be seen from line 5 that the result of the "add word" instruction is put in register d2. In line 6 this result is moved to register d4, rotated (taking into account the differing conventions on high and low bytes between the 8088 and the 68020) and moved to the address previously set up in register a0. The result however remains in register d2.

Turning to Figure 2C, there is shown the 68020 code string for the label 07aA00 which is a "jump on even parity" instruction. It will be seen from line 1 that the result byte from d2 is moved to register d4, which has previously been zeroed. A look up is then performed in a parity table "PF table", which hold for each 256 values of the byte result, the appropriate parity value 0 or 1. This parity value is placed in register d4 and, in line 2, a byte test operation is performed to provide the subject for the jump in line 3.

A similar problem arises with the auxiliary carry flag which is not provided in the 68020 processor. This is handled in a manner analogous to that described above for the parity flag.

Even taking into consideration the fact that there are slightly less than 256 op-codes and the fact that not every addressing mode is appropriate for each op-code, the creation of the 68020 code strings as described above is a major undertaking. With knowledge of the amount of coding typically required at a single location, it is thought that approximately 300,000 lines of coding are involved. To write, and perhaps more importantly to debug this amount of code probably would be regarded as impractical for a commercial product. According to a further aspect of this invention, however, a method is

provided for the automatic generation of the necessary coding. This will now be described in detail.

A separate code generator is provided for each 8088 op-code or each category of op-codes. Continuing with the example of the POP instructions, a "make POP" generator is provided and a specific example of this is shown in the listing which is Figure 3. Referring to the diagram which is Figure 4, it will be seen that a primitive preprocessing stage takes a generalised generator program such as that exemplified in the listing of Figure 8 to produce a specific generator program for the host microprocessor. In this preprocessing stage, information is taken from a register mapping table which maps the 8088 registers on to the registers available on the host. It is, if necessary, possible to map an 8088 register onto a memory address. The primitive preprocessing stage also makes reference to a hex look-up table, which provides hexadecimal equivalents.

The specific generator program, as illustrated in Figure 5, is then driven by op-code selectors to produce so-called pseudo-host code fragments, an example of which appears in Figure 9. These refer extensively to macros. As illustrated in Figure 6, a macro processing stage then converts the pseudo-code fragments into the required code string by referring to a macro library. There is contained in Figure 10 an excerpt from the macro library containing those macros referred to in the pseudo-host code fragments of Figure 9. The output of this macro processing stage is the code string 08fa00 as shown in Figure 2 which is, in a final assembly process illustrated in Figure 7,

converted into object code.

It will be well known to the skilled man that certain microcomputers based on the 8088 chip transfer processing control, under certain circumstances, to selected portions of 8088 code held in ROM. These code portions may represent service routines for communicating with input and output devices, for example. The service routines can also be called by application programs, providing a standard interface.

According to a preferred form of this invention, provision is made for service routines which are in 68020 code and can thus be executed by the host processor in "native" mode, that is to say without reference to the jump table. The service routines can be written in a high level language such as "C" and then compiled. This is a considerable advantage for programmers.

The 8088 command transfers control to a memory location which - instead of marking the beginning of a sequence of 8088 commands, terminating with IRET - contains a pseudo-8088 command. By "pseudo-command" is meant an op-code which is not given a definition in the 8088 instruction set. Depending upon the operand of the pseudo-command, a program call is made to an indexed high level language routine. By this ingenious means it is possible to call a high level language routine in a manner which is transparent to software running on the emulation. This use of a pseudo-command can be better understood by reference to Figures 11A and 11B which illustrate in diagrammatic form the use of a software interrupt

respectively in conventional form and in accordance with a preferred feature of this invention. Referring to Figure 11A, the instruction INT n in the program which is running causes control to be passed from the CPU to a service routine defined by the Interrupt Vector Table (IVT) and the INT operand n. The service routine comprises a series of 8088 instructions terminated by the IRET instruction. Turning now to Figure 11B, the instruction INT n results in control being transferred to a location defined again through the IVT. At that location, there is the pseudo-command BOP n causing a program call to be made at location n in a high level language program store. The service routine may typically be written in C. The service routine returns control to the BOP instruction string and the emulation process continues as previously described. Typically the next instruction following the BOP command will be the 8088 instruction IRET.

In addition to providing for fast running of fixed service routines, this technique enables the host processor to communicate effectively with input and output devices. It should be understood that this invention has been described by way of example only and whilst those examples have been confined to emulation of the Intel 8088 on a Motorola microprocessor, the invention should not be regarded as restricted in any sense to this application.

In the described example, the jump table is accessed using the first two bytes of the 8088 instruction which in a typical case

comprise the operation and addressing mode respectively. This second byte may in most cases be regarded as the operand addressor since it points to or contains the operand. As has been explained the second byte may occasionally represent a second instruction and there may still be advantage in dealing with both bytes together. In some other cases, the value of the second byte is redundant to the jump process. In other emulations the operation code and such functions as the operand addressor may not form the first two bytes. In some cases it will be appropriate to use the operation code and the next most significant element in the instruction stream, for the purposes of accessing the host code strings.

Whilst a jump table is the preferred manner of accessing the host instruction strings, other methods may be employed. Thus, with appropriate indexing, control might be passed directly to the start of the host instruction string.

The described method of generating the host instruction strings is felt to have considerable advantages but alternatives within the scope of this invention will exist.

The feature by which each location contains coding for addressing the next instruction; the manner in which interrupts are handled and the manner in which flags are dealt with are believed to represent further and separately novel advances.

CLAIMS

1. Data processing means adapted to be controlled by sequential instructions, a substantial number of which comprise an operation code selected from a set of n such codes and a qualifying code selected from a set of m such codes, the data processing means comprising a store having approximately n times m locations with each location corresponding to a consistent combination of operating code and qualifying code and holding a series of instructions corresponding to the said operating code and qualifying code.
2. A process for controlling the operation of a data processing unit in accordance with a received series of instructions, where at least some instructions each comprise an operator and an operand addressor, there being a finite number of permissible combinations of operator and operand addressor, the process comprising the steps of holding a plurality of instruction strings, one for each said permissible combination of operator and operand addressor, and inputting to the data processing unit for each received instruction, the instruction string corresponding with said operator and operand addressor combination.

3. A computer including processing means; first store means for storing a series of instructions, a substantial number of which instructions comprise an operator and an addressing mode; second store means having a plurality of locations corresponding respectively with permissible combinations of said operator and said addressing mode, and being adapted to hold at each said location an instruction string; and control means adapted to input in sequence to said processing means instruction strings from locations in said second store means corresponding respectively with instructions from said first store means.
4. A computer as claimed in Claim 3, further comprising table means having entries corresponding with respective said locations, each entry comprising the address in said second store means of the said instruction string.
5. A computer as claimed in claim 3, wherein each instruction string is arranged to provide said control means with information relating to the address in said store means of the next instruction.